



VECTOR ANALYSIS

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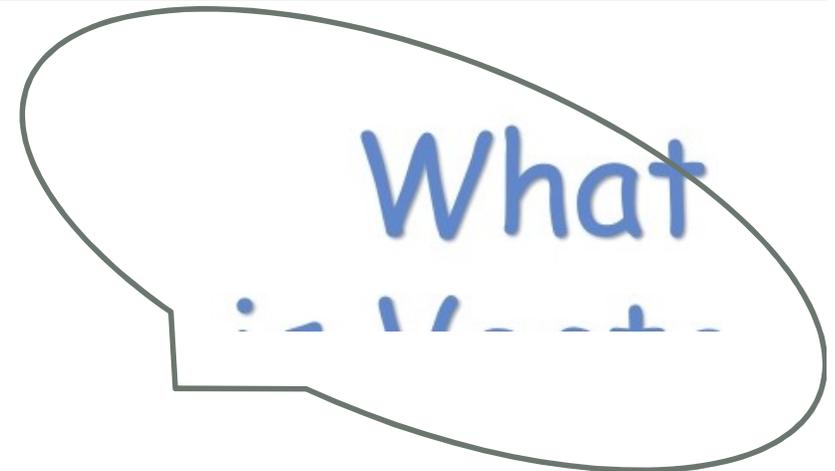
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 - Scalar Multiplication of two Vectors
 - Vector Multiplication of two Vectors



A scalar is a physical quantity
has only a magnitude.

Examples:

- Mass
- Length
- Temperature
- Volume

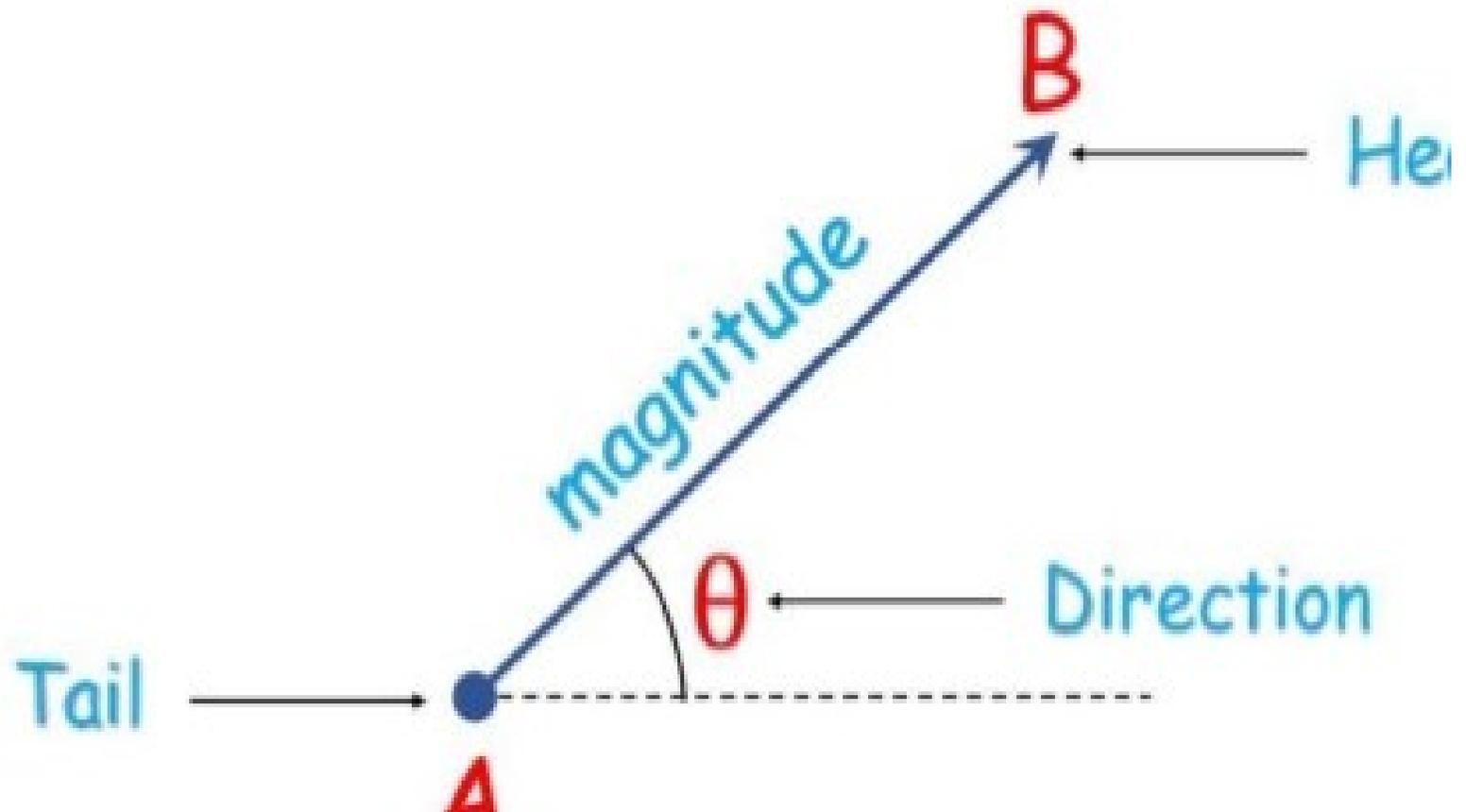


A vector is a physical quantity that has both a magnitude and a direction.

Examples:

- Position
- Displacement
- Acceleration
- Momentum

Representation of a vector



Types of Vectors

Unit vectors

- A given vector can be expressed as a p its magnitude and a unit vector.
- For example \vec{A} may be represented as,

$$\vec{A} = A \hat{A}$$

A = magnitude of \vec{A}

Parallel Vectors

Two vectors are said to be parallel vectors if they have same direction.



Anti-parallel Vectors

Two vectors are said to be anti-parallel if they are in opposite direction.



Equal Vectors

Two parallel vectors are said to be equal if they have same magnitude.



Negative Vectors

Two anti-parallel vectors are said to be negative vectors, if they have same magnitude



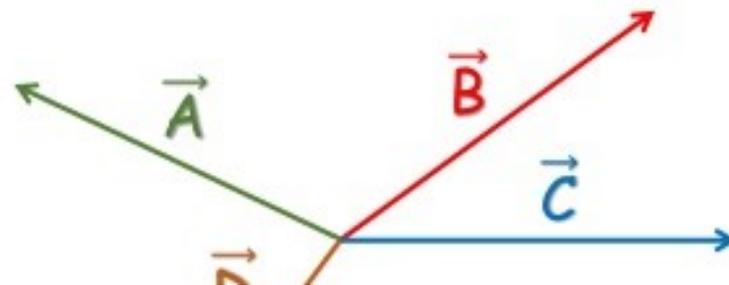
Collinear Vectors

Two vectors are said to be collinear if they act along a same line.



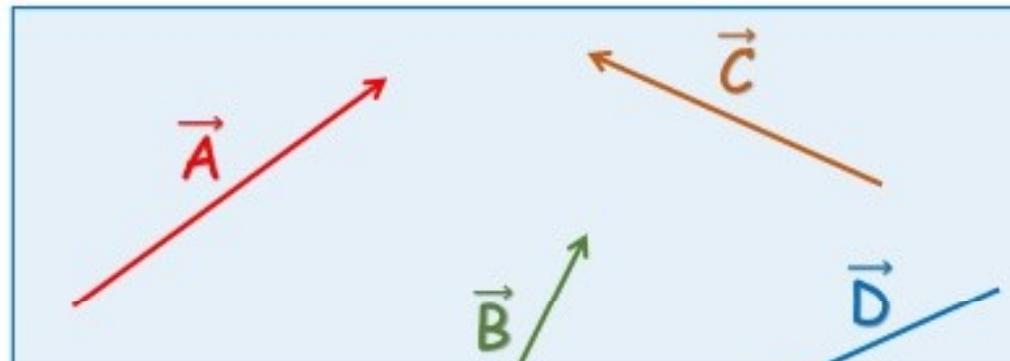
Co-initial Vectors

Two or more vectors are said to be co-initial vectors, if they have common initial



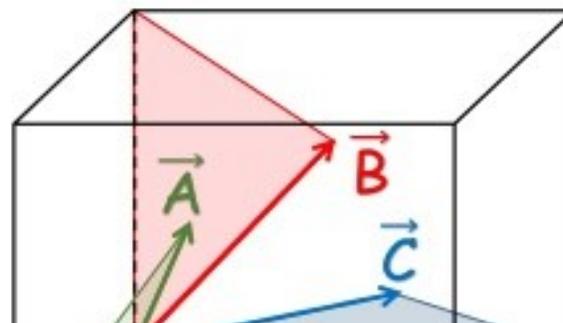
Coplanar Vectors

Three or more vectors are said to be coplanar vectors, if they lie in the same plane.



Non-coplanar Vectors

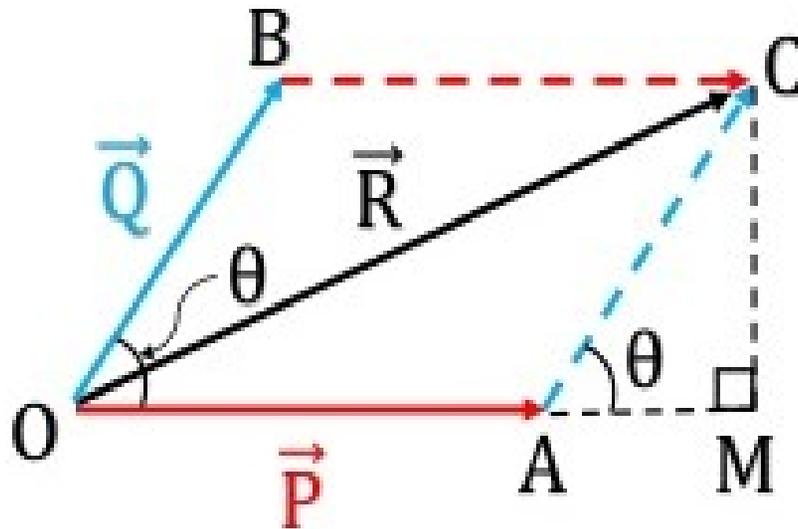
Three or more vectors are said to be non-coplanar vectors, if they are distributed in space.



Vectors

Addition

Magnitude of Resultant



In $\triangle OCM$,

$$OC^2 = OM^2 + CM^2$$

$$OC^2 = OA^2 + 2OA \times AM$$

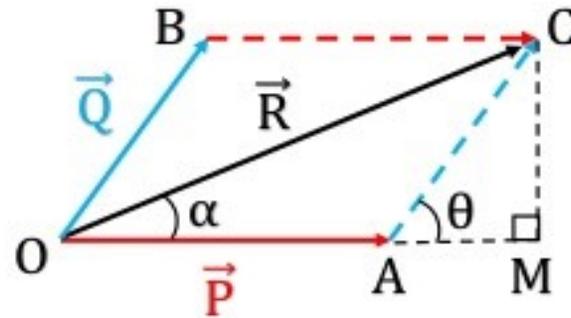
In $\triangle CAM$,

$$\cos \theta = \frac{AM}{AC} \Rightarrow AM = AC \cos \theta$$

$$OC^2 = OA^2 + 2OA \times AM + AC^2$$

$$R^2 = P^2 + 2P \times Q \cos \theta$$

Direction of Resultant



In ΔCAM ,

$$\sin \theta = \frac{CM}{AC} \Rightarrow CM = AC \sin \theta$$

In ΔOCM ,

$$\tan \alpha = \frac{CM}{OM}$$

$$\tan \alpha = \frac{CM}{OA+AM}$$

$$\tan \alpha = \frac{AC \sin \theta}{OA+AM}$$

Case I - Vectors are parallel ($\theta = 0^\circ$)

SPECIAL CASE

$$\vec{P} + \vec{Q} = \vec{R}$$

Magnitude:

$$R = \sqrt{P^2 + 2PQ \cos 0^\circ + Q^2}$$

$$R = \sqrt{P^2 + 2PQ + Q^2}$$

$$R = \sqrt{(P + Q)^2}$$

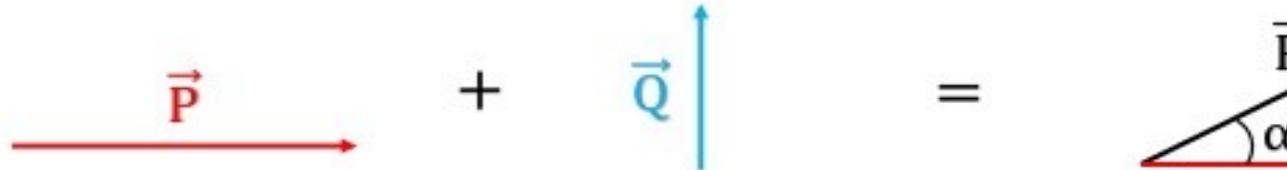
Direction:

$$\tan \alpha = \frac{Q \sin 0^\circ}{P + Q \cos 0^\circ}$$

$$\tan \alpha = \frac{0}{P + Q} = 0$$

Case II - Vectors are perpendicular ()

SPECIAL CASE



Magnitude:

$$R = \sqrt{P^2 + 2PQ \cos 90^\circ + Q^2}$$

$$R = \sqrt{P^2 + 0 + Q^2}$$

Direction:

$$\tan \alpha = \frac{Q \sin 90^\circ}{P + Q \cos 90^\circ}$$

Case III - Vectors are anti-parallel ()

SPECIAL CASE



Magnitude:

$$R = \sqrt{P^2 + 2PQ \cos 180^\circ + Q^2}$$

$$R = \sqrt{P^2 - 2PQ + Q^2}$$

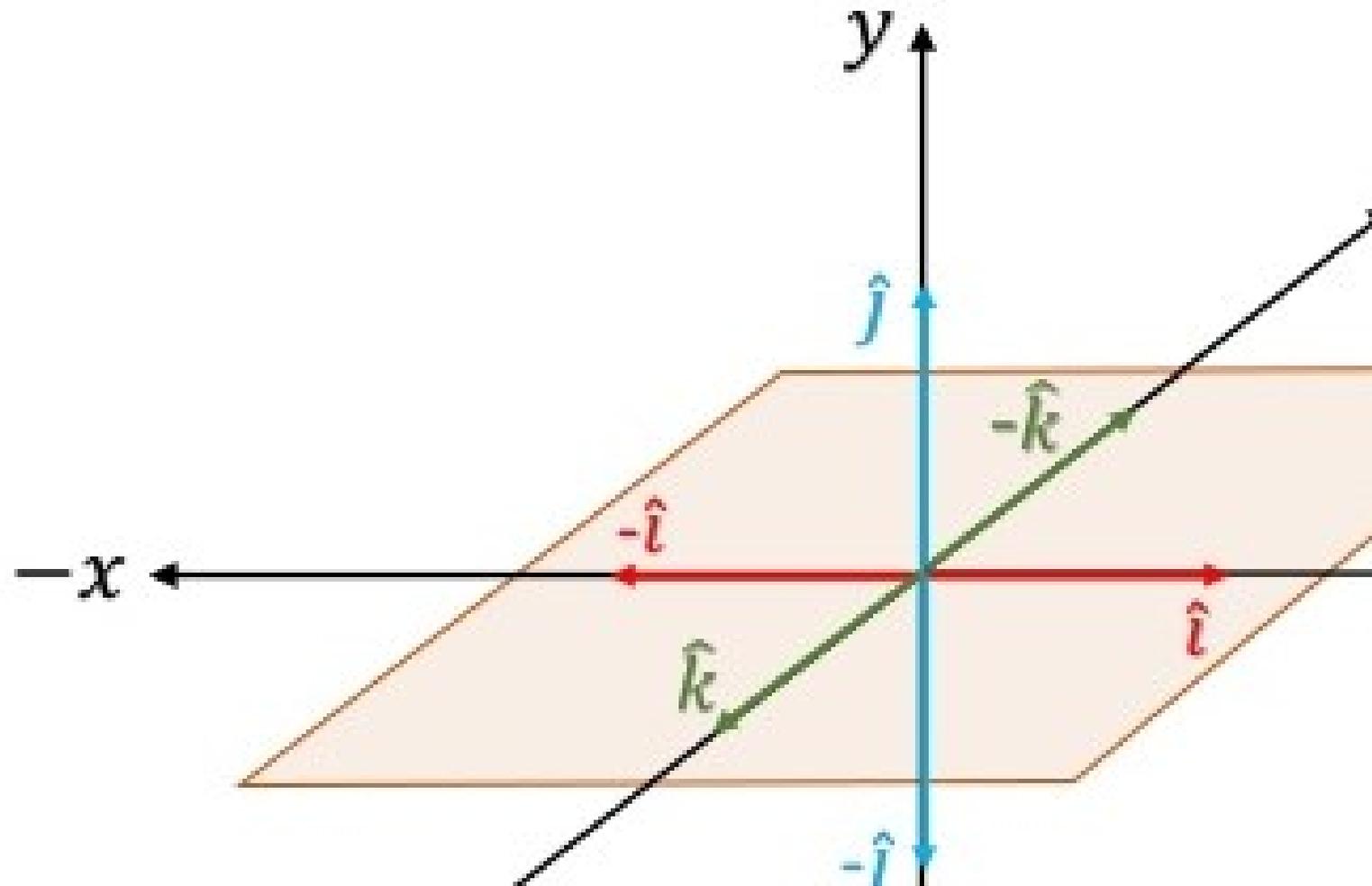
$$R = \sqrt{(P - Q)^2}$$

Direction:

$$\tan \alpha = \frac{Q \sin 180^\circ}{P + Q \cos 180^\circ}$$

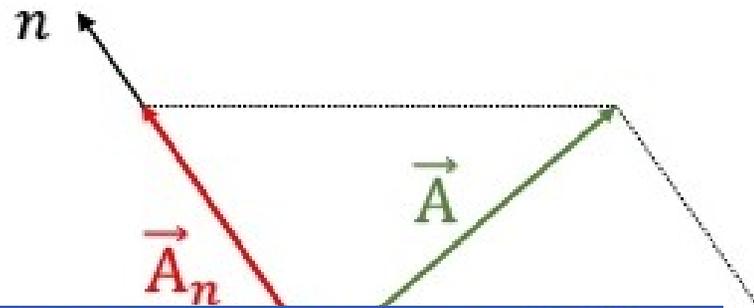
If $P > Q$: $\alpha =$

Cartesian unit vect

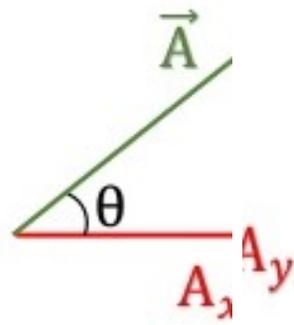
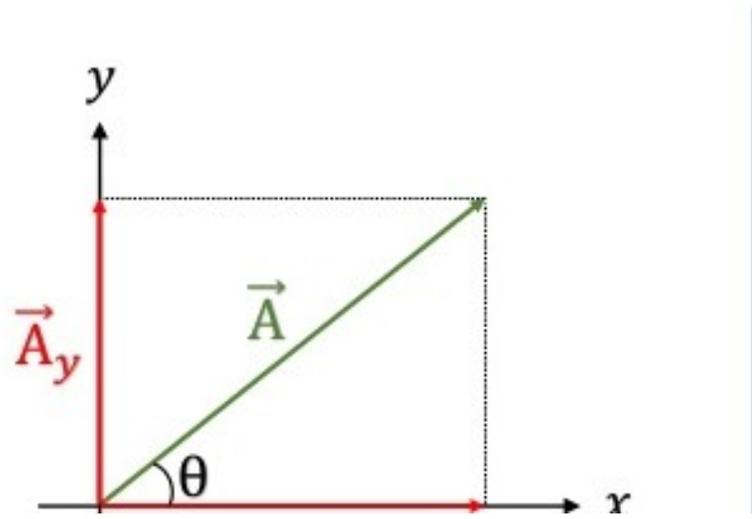


Resolution of a Vector

It is the process of splitting a vector into two or more vectors in such a way that their combined effect is same as the given vector.



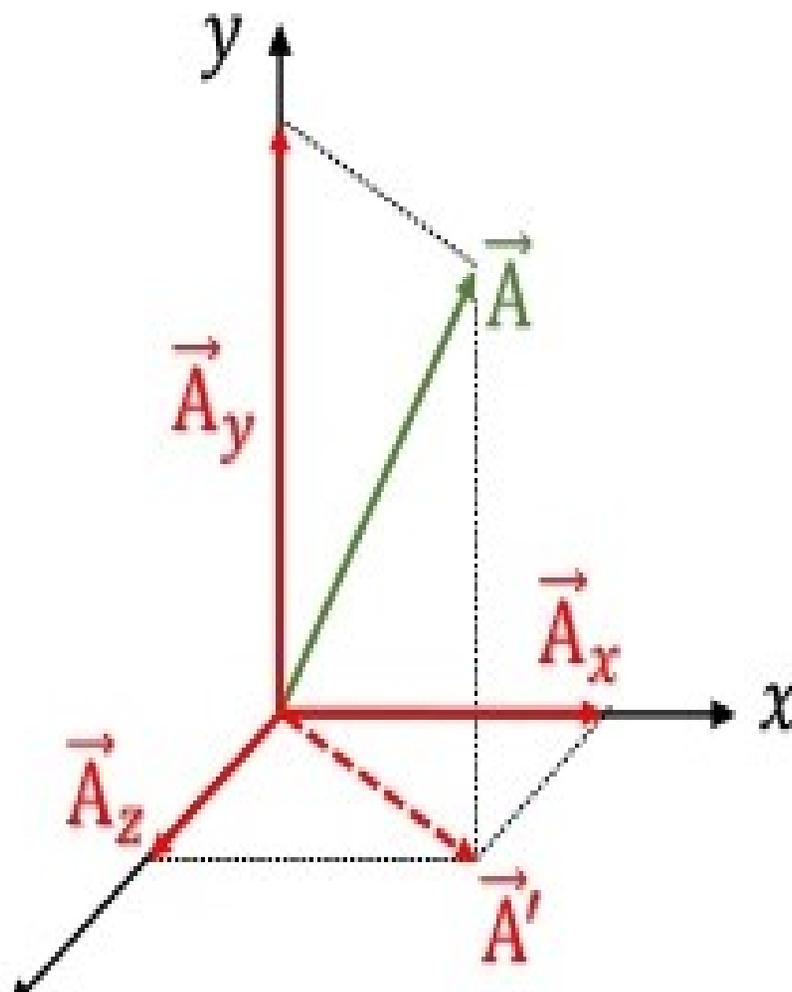
Rectangular Components of 2D V



$$\sin \theta = \frac{A_y}{A} \Rightarrow \boxed{A_y}$$

Δ...

Rectangular Components of 3D Vec



$$\vec{A} = \vec{A}' + \vec{A}_y$$

$$\vec{A} = \vec{A}_x + \vec{A}_z$$

$$\vec{A} = \vec{A}_x + \vec{A}_y$$

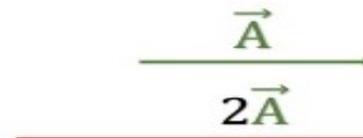
$$\vec{A} = A_x \hat{i} + A_y \hat{j} + A_z \hat{k}$$

Multiply

A) Multiplying a vector by a scalar

- If we multiply a vector \vec{A} by a scalar s , new vector.
- Its magnitude is the product of the magnitude of \vec{A} and the absolute value of s .

If s is positive:



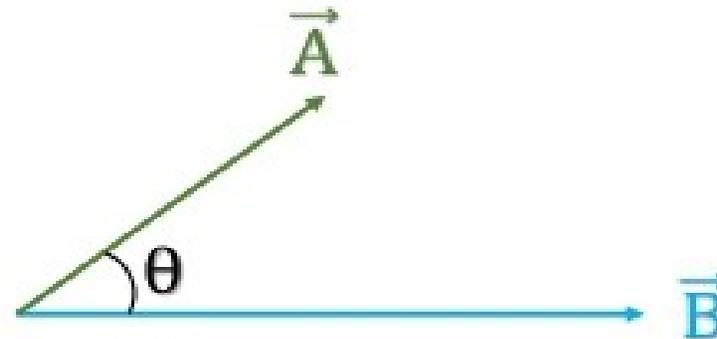
If s is negative:



B) Multiplying a vector by a vect

- There are two ways to multiply a vector by a vector:
- The first way produces a scalar quantity called as scalar product (dot product).

Scalar product



Examples of scalar product

$$W = \vec{F} \cdot \vec{s}$$

$$W = Fs \cos \theta$$

$W =$ work done

$F =$ force

$$P = \vec{F} \cdot \vec{v}$$

$$P = Fv \cos \theta$$

$P =$ power

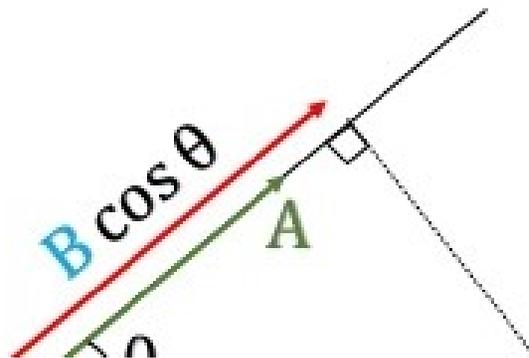
$F =$ force

Geometrical meaning of Scalar dot p

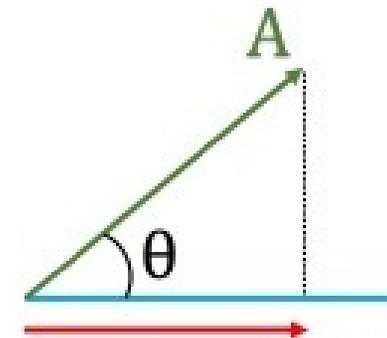
A dot product can be regarded as the of two quantities:

1. The magnitude of one of the vectors

$$\vec{A} \cdot \vec{B} = A(B \cos \theta)$$



$$\vec{A} \cdot \vec{B} = (A \cos \theta) B$$



Properties of Scalar product

1

The scalar product is commutative.

$$\vec{A} \cdot \vec{B} = AB \cos \theta$$

$$\vec{B} \cdot \vec{A} = BA \cos \theta$$

2

The scalar product is distributive over addition.

3

The scalar product of two perpendicular vectors is zero.

$$\vec{A} \cdot \vec{B} = AB \cos 90^\circ$$

4

The scalar product of two parallel vectors is maximum positive.

$$\vec{A} \cdot \vec{B} = AB \cos 0^\circ$$

5

The scalar product of two anti vectors is maximum ne

$$\vec{A} \cdot \vec{B} = AB \cos 180$$

6

The scalar product of a vector with itself is equal to the square of its magnitude

7

$$\vec{A} \cdot \vec{A} = AA \cos 0^\circ$$

The scalar product of two same unit vectors is one and two different unit vectors is zero

$$\hat{i} \cdot \hat{i} = \hat{j} \cdot \hat{j} = \hat{k} \cdot \hat{k} = (1)(1) \cos 0$$

Calculating scalar product using com

Let us have

$$\vec{A} = A_x \hat{i} + A_y \hat{j} + A_z \hat{k}$$

$$\vec{B} = B_x \hat{i} + B_y \hat{j} + B_z \hat{k}$$

then

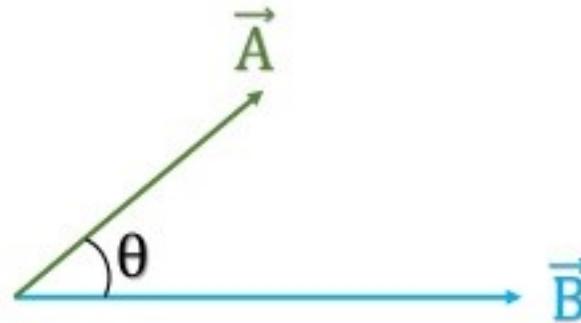
$$\vec{A} \cdot \vec{B} = (A_x \hat{i} + A_y \hat{j} + A_z \hat{k}) \cdot (B_x \hat{i} + B_y \hat{j} + B_z \hat{k})$$

$$\vec{A} \cdot \vec{B} = A_x \hat{i} \cdot (B_x \hat{i} + B_y \hat{j} + B_z \hat{k})$$

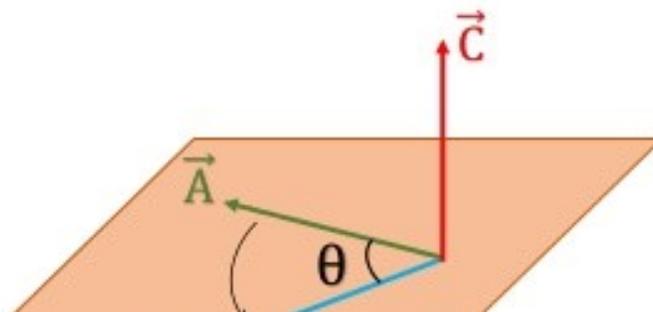
$$= A_x B_x \hat{i} \cdot \hat{i} + A_x B_y \hat{i} \cdot \hat{j} \\ + A_y B_x \hat{j} \cdot \hat{i} + A_y B_y \hat{j} \cdot \hat{j} \\ + A_z B_x \hat{k} \cdot \hat{i} + A_z B_y \hat{k} \cdot \hat{j}$$

$$= A_x B_x (1) + A_x B_y (0) \\ + A_y B_x (0) + A_y B_y (1) \\ + A_z B_x (0) + A_z B_y (0)$$

Vector product



Right hand rule



Examples of vector product

$$\vec{\tau} = \vec{r} \times \vec{F}$$

$$\tau = rF \sin \theta \hat{n}$$

τ = torque

r = position

$$\vec{L} = \vec{r} \times \vec{p}$$

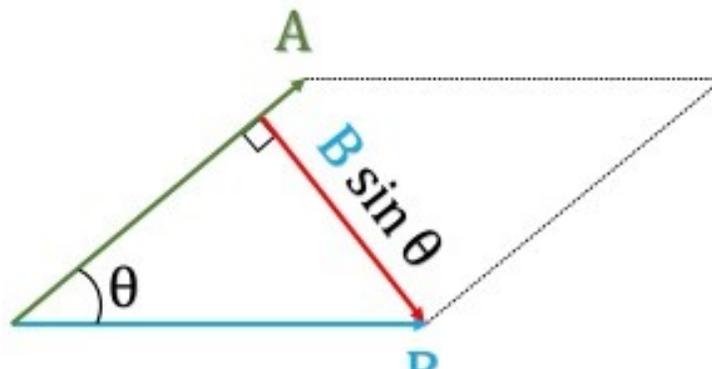
$$L = rp \sin \theta$$

L = angular momentum

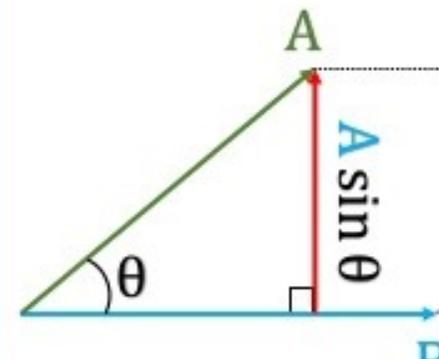
r = position

Geometrical meaning of Vector product

$$|\vec{A} \times \vec{B}| = A(B \sin \theta)$$



$$|\vec{A} \times \vec{B}| = (A \sin \theta) B$$



Properties of Vector p

1

The vector product is anti-commutative.

$$\vec{A} \times \vec{B} = AB \sin \theta \hat{n}$$

$$\vec{B} \times \vec{A} = BA \sin \theta (-\hat{n}) = -\vec{A} \times \vec{B}$$

2

The vector product is distributive over addition.

3

The magnitude of the vector product of two perpendicular vectors is maximum.

$$|\vec{A} \times \vec{B}| = AB \sin 90^\circ = AB$$

4

The vector product of two parallel vectors is a null vector.

$$\vec{A} \times \vec{B} = AB \sin 0^\circ \hat{n}$$

5

The vector product of two antiparallel vectors is a null vector.

$$\vec{A} \times \vec{B} = AB \sin 180^\circ \hat{n}$$

6

The vector product of a vector with itself is a null vector.

$$\vec{A} \times \vec{A} = AA \sin 0^\circ \hat{n}$$

7

The vector product of two same vectors is a null vector

$$\hat{i} \times \hat{i} = \hat{j} \times \hat{j} = \hat{k} \times \hat{k}$$

8

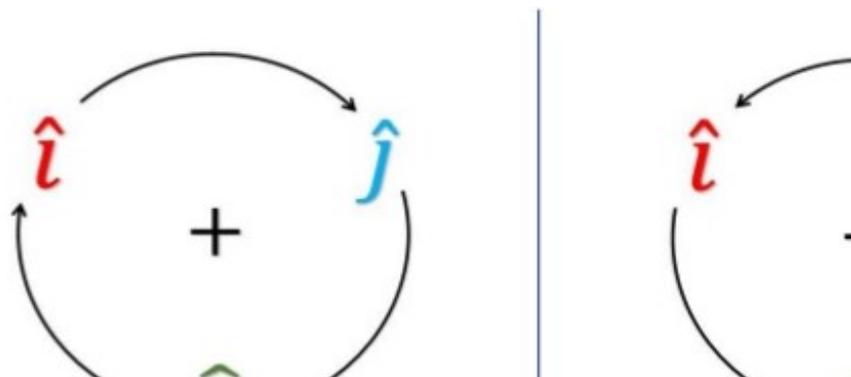
The vector product of two different vectors is a third unit vector

$$\hat{i} \times \hat{j} = \hat{k}$$

$$\hat{j} \times \hat{k} = \hat{i}$$

$$\hat{j} \times \hat{i} = -\hat{k}$$

$$\hat{k} \times \hat{i} = \hat{j}$$



Calculating vector product using comp

Let us have

$$\vec{A} = A_x \hat{i} + A_y \hat{j} + A_z \hat{k}$$

$$\vec{B} = B_x \hat{i} + B_y \hat{j} + B_z \hat{k}$$

then

$$\vec{A} \times \vec{B} = (A_x \hat{i} + A_y \hat{j} + A_z \hat{k}) \times (B_x \hat{i} + B_y \hat{j} + B_z \hat{k})$$

$$\vec{A} \times \vec{B} = A_x \hat{i} \times (B_x \hat{i} + B_y \hat{j} + B_z \hat{k})$$

$$\vec{A} \times \vec{B} = \hat{i} (A_y B_z - A_z B_y) - \hat{j} (A_x B_z - A_z B_x) + \hat{k} (A_x B_y - A_y B_x)$$

$$\begin{aligned} &= A_x B_x \hat{i} \times \hat{i} + A_x B_y \hat{i} \times \hat{j} \\ &+ A_y B_x \hat{j} \times \hat{i} + A_y B_y \hat{j} \times \hat{j} \\ &+ A_z B_x \hat{k} \times \hat{i} + A_z B_y \hat{k} \times \hat{j} \end{aligned}$$

$$\begin{aligned} &= A_x B_x (\vec{0}) + A_x B_y (\hat{k}) + \\ &+ A_y B_x (-\hat{k}) + A_y B_y (\vec{0}) \\ &+ A_z B_x (\hat{j}) + A_z B_y (-\hat{i}) \end{aligned}$$

$$\vec{A} \times \vec{B} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ A_x & A_y & A_z \\ B_x & B_y & B_z \end{vmatrix}$$



THANK YOU

ALL THE BEST

<https://www.slideshare.net/KhanSaif2/1-scalars-vectors>

<https://www.slideshare.net/KunjPatel4/vector-calculus-and-linear-algebra>